

Referent/in

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Titel

Ein robotischer Gangsimulator zur Überprüfung orthopädischer und prothetischer Hilfsmittel

Coauthors

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Zusammenfassung

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Einführung

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Methodik

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Ergebnisse

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Schlußfolgerung

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Literaturreferenzen

[1] Reliability and usage of clinical parameters for foot assessment. Cuppens K, Knippels I, Broeckx M, Saey T, Van den Herrewegen I, Luca S, Labey L, Peeraer L, the ISPO-World Congress, Lyon, France, June 2015

[2] Development of a measurement protocol to define shoe parameters: deformation of shoe sole during running; De Raeve E, Vertommen H, Dewindt W, Peeraer L, Footwear Science, June 2011

[3] Development of a tool to optimize individual alignment of lower leg prostheses. A combined in vitro, in silico and in vivo approach. De Raeve E, Knippels I, Saey T, Muraru L, Sels R, Biesbrouck E, Janssen P, Creylman V, Labey L, Peeraer L, OT world Congress, Leipzig, Germany, May 2014