

## Author

Jakubowitz, Eike (Hannover DE) | Dr. Dipl.-Ing.

Orthopädische Klinik der MHH - Institut für Orthopädische Bewegungsdiagnostik, Labor für Biomechanik

## Title

Intrinsic gripping intelligence from soft robotics in upper limb prosthetics: initial clinical results

## Coauthors

Catalano M, Bicchi A, Fleischer-Lück B, Vollmer C, Obermeier A

## Summary

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## Introduction

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## Methods

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## Results

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## Conclusion

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## References

1. Catalano MG, Grioli G, Farnioli E, Serio A, Piazza C, Bicchi A: Adaptive synergies for the design and control of the Pisa/IIT SoftHand. *Int J Robotics Res.* 2014; 33:768-82.
2. Kyranou I, Krasoulis A, Erden MS, Nazarpour K, Vijayakumar S: Real-time classification of multi-modal sensory data for prosthetic hand control. *6th IEEE Int. Conf. on Biomedical Robotics and Biomechanics* 2016;536-41.